

Template for Preparation of Papers for ICMT2017 Conference Proceedings

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Abstract – These instructions give you the basic guidelines for preparing papers for ICMT2017 conference proceedings. Please use this document as a “template” to prepare your manuscript. For paper submission, follow the instructions on the Conference website. <http://icmt2017.hcmut.edu.vn>

Keywords - List keywords here (separated by a comma). No more than three.

1 INTRODUCTION

These are instructions for authors typesetting for the 17th International Conference on Mechatronics Technology (ICMT2017). This document has been prepared using the required conference format. **Please use this document as a “template” to prepare your manuscript. For submission guidelines, follow instructions on paper submission system as well as the conference website. Do not delete the blank line immediately above the first section; it sets the footnote at the bottom of this column. The paper is to be written in two-column format and be right and left justified.** The column width should be 84.5mm. The gap between the two columns should be 7mm.

1.1 Instructions for Authors

In order for the proceedings to be ready for distribution at the conference, an electronic copy of the final version of your paper (camera ready - PDF format) must be submitted via the on-line paper submission link via “Paper Submission” web page. Please follow the submission instructions shown on this page.

2 FORMATTING INSTRUCTIONS

MS Word Authors: please try to use the paragraph styles contained in this document.

2.1 Page/Font Settings

Style files and templates provided here have been created to ensure that margin requirement is adequately met. If, for some reason, you are not able to use provided templates or style files, please observe the following margins and font settings strictly.

Tab. 1: Page Margins

Paper Size	(21x29.7) cm
Top Margin (1st page)	1.9 cm
Top Margin (rest)	2cm
Left Margin	1.7cm
Right Margin	1.7cm
Bottom Margin	2.2cm
Text Width	17.6cm
Text Height	25.5cm
Column Width	8.45cm
Column Separation	0.7cm

Tab. 2: Font Settings

Title	Times New Roman, 16pt, bold
Author List	Times New Roman, 11pt
Authors' Address	9pt
Abstract, Key Words	9pt
Section Titles	11pt, uppercase, bold
Subsection Titles	10pt, bold
Normal Text	10pt
Table/Figure Captions	9pt
Footnotes	8pt
References	9pt

2.2 Section and Subsection Headings

Number section and subsection headings consecutively in Arabic numbers and type them in bold. Avoid using too many capital letters. If any further subdivision of a subsection is needed the titles should be 10 point and flushed left.

2.3 Main Text

Use Times New Roman with font size 10 point for text (character size). Paragraphs are separated by 6 point and with no indentation. You may type on plain white A4 paper. Typing area should not exceed 175mm x 255mm. The text should be prepared with a double column format and single line spacing.

2.4 Tables

All tables must be centered in the column and numbered consecutively (in Arabic numbers). Table headings should be placed above the table. Place tables as close as possible to where they are mentioned in the main text (see Table1 and Table2).

2.5 Figures

All illustrations should be original drawings or photographic prints of originals. Photographs should be glossy prints. Photocopies are often not good enough and should be avoided. All illustrations must be numbered consecutively, using Arabic numbers. Center figure captions beneath the figure (see Figure 1). If possible, do not assemble figures at the back of your article, but place them as close as possible to where they are mentioned in the main text. No part of a figure should go beyond the typing area. Captions should appear below graphical objects, as in Figure 1.

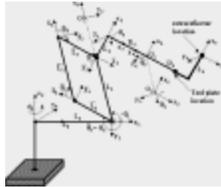


Fig. 1: The caption

Color and grayscale figures should be prepared with 400 dpi resolution and saved with no compression; monochrome figures should be prepared with 600 dpi resolution and saved with no compression.

2.6 Mathematical Formulas

Mathematical formulas should be roughly centered and have to be numbered as formula (1).

$${}^0T_6 = ({}^0T_1)({}^1T_2)(T_{\text{par}})({}^3T_3)({}^3T_4)({}^4T_5)({}^5T_6) \quad (1)$$

2.7 References

References are listed by order of first appearance and the reference items are represented as Arabic numbers in square brackets, e.g. [1].

References are titled as “REFERENCES” with 11pt bold font, flush left and no indent, paragraph spacing before 12pt and after 6pt. The body text of references is formatted as 9pt Times New Roman, initial paragraph no indent, hanging indent 0.57cm, single space and paragraph spacing after 2pt.

For journal paper references, the information should be included such as author name, article title, journal title, volume number, issue number, page number, year. Similarly, author name, book name, edition number, publisher and year should be included for book references. Examples of both journal paper and book references are shown at the end of this template.

● Proceedings or Books

Use “[C].” after symposium title, or “[M].” after book title. Give publisher and its location. Give date as (year, month) or (year).

Journal Article

Include the issue number in parentheses immediately after the volume number. Give page numbers.

Article in Proceedings or Books

Use “[C]//” before symposium title, or “[M]//” before book title. Give publisher and its location. Give date as (year, month) or (year). Include page numbers.

● Fine tuning

Do not end a page with a section or subsection heading.

Do not include page numbers in the text

Large figures, tables and mathematical equations may span both columns

3 PAPER SUBMISSION

After proofreading your paper, it must be submitted via the on-line submission link via the 7 website in camera ready PDF formats.

REFERENCES

- [1] J. Smith, “Static friction effects during for tasks and their implications for manipulator design,” *Int. J Robot. Res.*, vol. 15, no. 6, pp. 508–510, 1998.
- [2] M. T. Mason and J. K. Salisbury, *Robot Hands and the Mechanics of Manipulation*. Cambridge, MA: MIT Press, 1985.
- [3] B. J. Li and R. A. Freeman, “Synthesis of actively adjustable springs by antagonistic redundant actuation,” *ASME J. Dyn Syst., Measur. Contr.*, vol. 114, pp. 454–461, 1992.